

## Upgraded cylindrical photoelectric sensor

### ■ Features

- Detects up to 20m (Through-beam type)
- Superior noise resistance with digital signal processing
- High-speed response time under 1ms
- Reverse power polarity and short-circuit (overcurrent) protection circuit
- Suitable for sensing in narrow space (Narrow beam type)
- External sensitivity adjustment (Diffuse reflective, Retroreflective type)
- Light ON, Dark ON switchable by control wire (Diffuse reflective, Retroreflective type)
- Excellent heat-resistance performance with glass lens (BR4M)
- Protection structure IP66 (IEC standard)

**⚠ Please read "Caution for your safety" in operation manual before using.**



Line-up

Connector Type

\* The model name with '-C' is connector type.

### ■ Specifications

Model	NPN open collector	BRP100-DDT	BR100-DDT	BRP400-DDT	BR400-DDT	BRP200-DDTN	BR200-DDTN	BRP3M-MDT	BR3M-MDT	BR4M-TDTD	BR4M-TDTL		
		BRP100-DDT-C	BR100-DDT-C	BRP400-DDT-C	BR400-DDT-C	BRP200-DDTN-C	BR200-DDTN-C	BRP3M-MDT-C	BR3M-MDT-C	BR4M-TDTD-C	BR4M-TDTL-C	BR20M-TDTL-C	
Model	PNP open collector	BRP100-DDT-P	BR100-DDT-P	BRP400-DDT-P	BR400-DDT-P	BRP200-DDTN-P	BR200-DDTN-P	BRP3M-MDT-P	BR3M-MDT-P	BR4M-TDTD-P	BR4M-TDTL-P		
		BRP100-DDT-C-P	BR100-DDT-C-P	BRP400-DDT-C-P	BR400-DDT-C-P	BRP200-DDTN-C-P	BR200-DDTN-C-P	BRP3M-MDT-C-P	BR3M-MDT-C-P	BR4M-TDTD-C-P	BR4M-TDTL-C-P	BR20M-TDTL-C-P	
Sensing type		Diffuse reflective				Narrow beam reflective		Retroreflective		Through-beam			
Sensing distance		100mm (★1)		400mm (★2)		200mm (★2)		0.1 to 3m (★3)		4m / 20m			
Sensing target		Translucent, Opaque materials						Opaque materials of Min. $\phi$ 60mm		Opaque materials of Min. $\phi$ 15mm			
Hysteresis		Max. 20% at rated setting distance											
Response time		Max. 1ms											
Power supply		12-24VDC $\pm$ 10% (Ripple P-P : Max. 10%)											
Current consumption		Max. 45mA											
Light source		Infrared LED (940nm)		Infrared LED (850nm)				Red LED (660nm)		Infrared LED (850nm)			
Sensitivity adjustment		Built-in VR									Fixed		
Operation mode		Light ON / Dark ON selectable by control wire (White)									Dark ON		Light ON
Control output		NPN or PNP open collector output • Load voltage : Max. 30VDC • Load current : Max. 200mA • Residual voltage $\Rightarrow$ NPN : Max. 1V, PNP : Min. (Power voltage - 2.5V)											
Protection circuit		Short-circuit protection, Reverse polarity protection											
Indication		Power indicator (Emitter) : Red LED, Operation indicator (Receiver) : Red LED											
Connection		Outgoing cable											
Insulation resistance		Min. 20M $\Omega$ (at 500VDC megger)											
Noise strength		$\pm$ 240V the square wave noise (pulse width : 1 $\mu$ s) by the noise simulator											
Dielectric strength		1000VAC 50/60Hz for 1 minute											
Vibration		1.5mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hours											
Shock		500m/s <sup>2</sup> (50G) in X, Y, Z directions for 3 times											
Ambient illumination		Sunlight : Max. 11,000lx, Incandescent lamp : Max. 3,000lx											
Storage temperature		-10 to 60°C (at non-freezing status) Storage : -25 to 70°C											
Ambient humidity		35 to 85%RH, Storage : 35 to 85%RH											
Protection		IP66 (IEC standard)											
Material		• BRP $\Rightarrow$ Case : PA (Nylon, Black), Lens : PC • BR $\Rightarrow$ Case : Brass, Ni-plate (BR-C : Ni-plate), Lens : PC					• Case $\Rightarrow$ BRP3M : PA (Nylon, Black) BR3M : Brass, Ni-plate (BR-C : Ni-plate) • Lens $\Rightarrow$ Acrylic			• Case $\Rightarrow$ Brass, Ni-plate (BR-C : Ni-plate) • Lens $\Rightarrow$ BR4M : Glass BR20M : PC			
Cable		• BR(P) $\Rightarrow$ 4P, $\phi$ 5mm, Length: 2m (Emitter of through-beam type: 2P, $\phi$ 5mm, Length: 2mm / Receiver: 3P, $\phi$ 5mm, Length: 2mm) • BR(P)-C $\Rightarrow$ M12 • BR(P)-C Series : M12 socket type : $\phi$ 5mm 4P, Length 3/5m, 22AWG, Core wire diameter : 0.08mm, No. of core wire : 60, Insulator diameter : $\phi$ 1.2mm											
Accessory	Individual	Adjustment driver					Adjustment driver, Reflector (MS-2)						
	Common	BR : Fixing nuts, Washer / BRP : Fixing nuts											
Approval		<b>CE</b>											
Unit weight		• BRP Series : Approx. 100g, BR Series : Approx. 120g • BRP-C Series : Approx. 20g, BR-C Series : Approx. 35g						• BR Series: Approx. 300g • BR-C Series: Approx. 110g					

\* (★1) Non-glossy white paper 50×50mm (★2) Non-glossy white paper 100×100mm.

(★3) Detecting distance and detecting target for Retroreflective type is rated based on mirror (MS-2). Detecting distance indicates possible reflective mirror setting range. Sensing under 0.1m is also available.

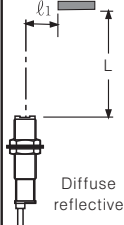
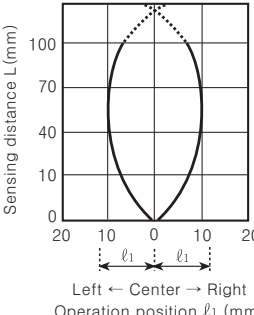
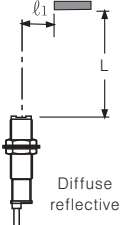
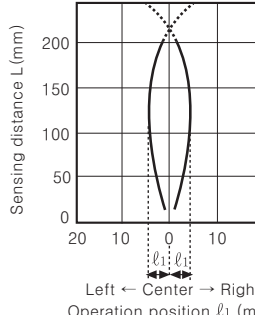
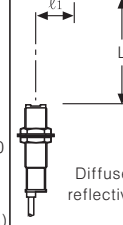
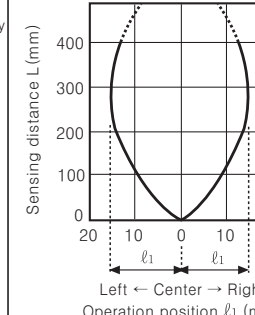
- (A) Photo electric sensor
- (B) Fiber optic sensor
- (C) Door/Area sensor
- (D) Proximity sensor
- (E) Pressure sensor
- (F) Rotary encoder
- (G) Connector/ Socket
- (H) Temp. controller
- (I) SSR/ Power controller
- (J) Counter
- (K) Timer
- (L) Panel meter
- (M) Tacho/ Speed/ Pulse meter
- (N) Display unit
- (O) Sensor controller
- (P) Switching power supply
- (Q) Stepping motor & Driver & Controller
- (R) Graphic/ Logic panel
- (S) Field network device
- (T) Production stoppage models & replacement

# BR Series

## Feature data

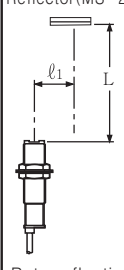
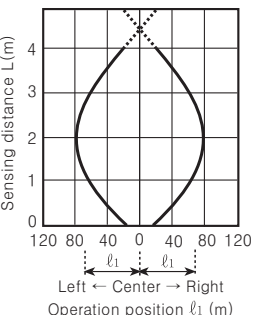
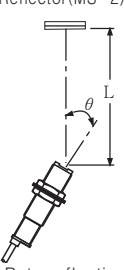
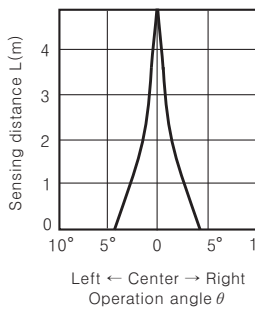
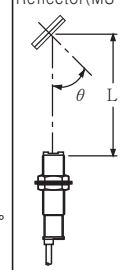
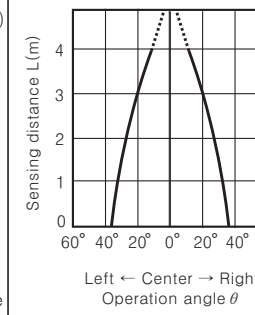
### Diffuse reflective/Narrow beam reflective

●BR100-DDT-□(-P)/BRP100-DDT-□(-P) ●BR200-DDTN-□(-P)/BRP200-DDTN-□(-P) ●BR400-DDT-□(-P)/BRP400-DDT-□(-P)

Sensing area(Diffusion type)		Sensing area(Narrow beam type)		Sensing area(Diffusion type)	
Measuring method	Data	Measuring method	Data	Measuring method	Data
Standard sensing target: Non-glossy white paper 50×50mm  Diffuse reflective		Standard sensing target: Non-glossy white paper 50×50mm  Diffuse reflective		Standard sensing target: Non-glossy white paper 100×100mm  Diffuse reflective	

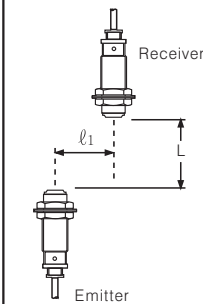
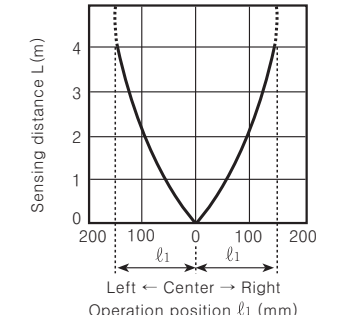
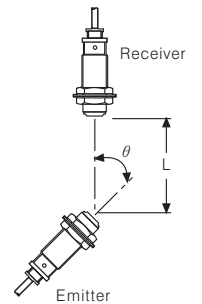
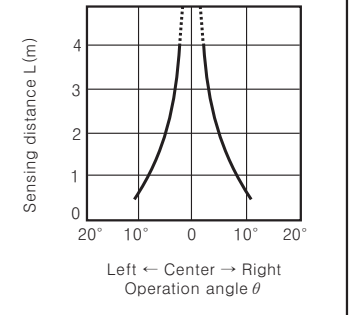
### Retroreflective

●BR3M-MDT-□(-P) / BRP3M-MDT-□(-P)

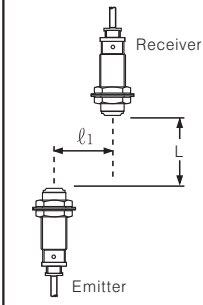
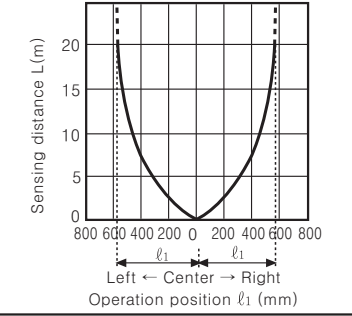
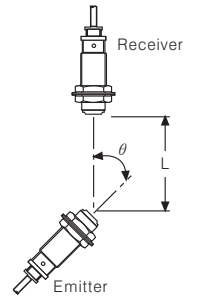
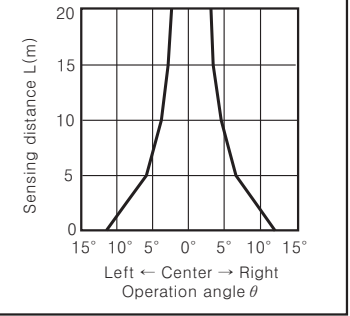
Parallel shifting characteristic		Sensor angle characteristic		Reflector angle characteristic	
Measuring method	Data	Measuring method	Data	Measuring method	Data
Reflector(MS-2)  Retroreflective		Reflector(MS-2)  Retroreflective		Reflector(MS-2)  Retroreflective	

### Through-beam

●BR4M-TDT□-□ / BR4M-TDT□-□-P

Parallel shifting characteristic		Angle characteristic	
Measuring method	Data	Measuring method	Data
			

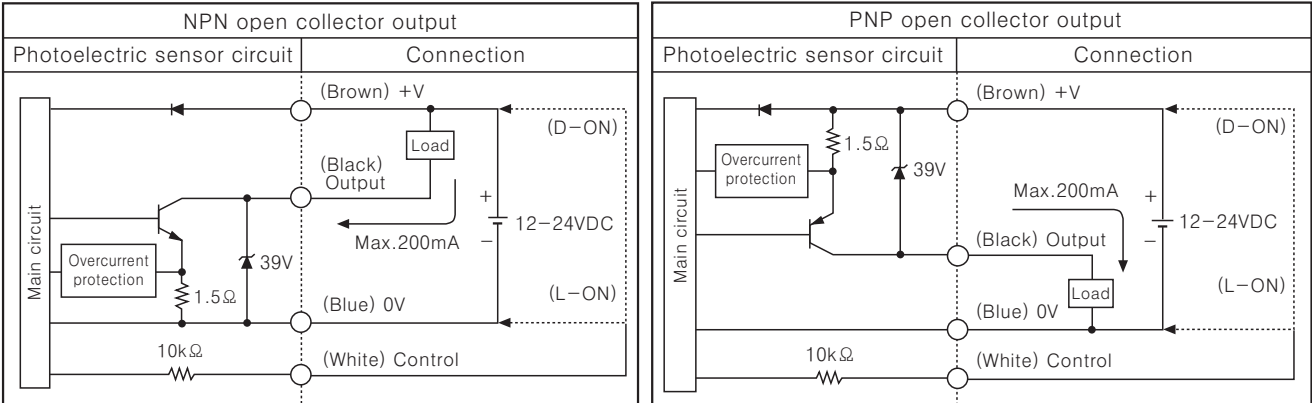
●BR20M-TDT□-□ / BR20M-TDT□-□-P

Parallel shifting characteristic		Angle characteristic	
Measuring method	Data	Measuring method	Data
			

# DC Cylindrical Housing Type

## Control output diagram

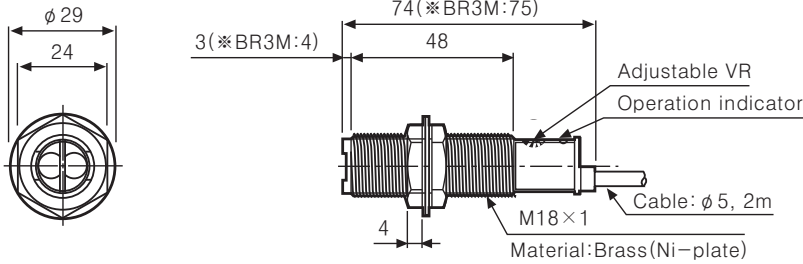
- BR(P)100-DDT-□ / BR(P)200-DDTN-□ / BR(P)400-DDT-□ ●BR(P)100-DDT-□-P / BR(P)200-DDTN-□-P / BR(P)400-DDT-□-P
- BR(P)3M-MDT-□ ●BR(P)3M-MDT-□-P
- BR20M-TDTD2-□ / BR20M-TDTL2-□(Receiver) ●BR20M-TDTD2-□-P / BR20M-TDTL2-□-P(Receiver)



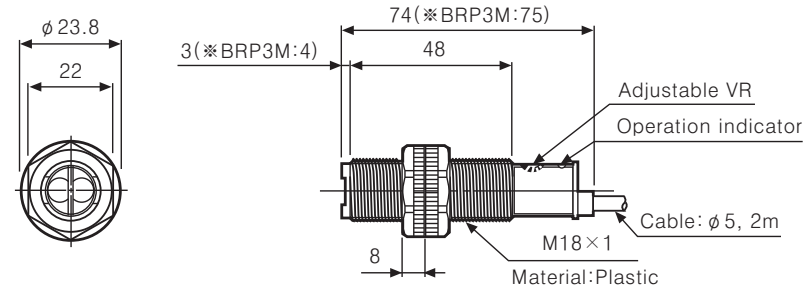
\*Select Light ON / Dark ON by control wire.  Light ON : Connect control wire to 0V  
 Dark ON : Connect control wire to +V  
 \*Control wire is available only for diffuse reflective type and retroreflective type.

## Dimensions

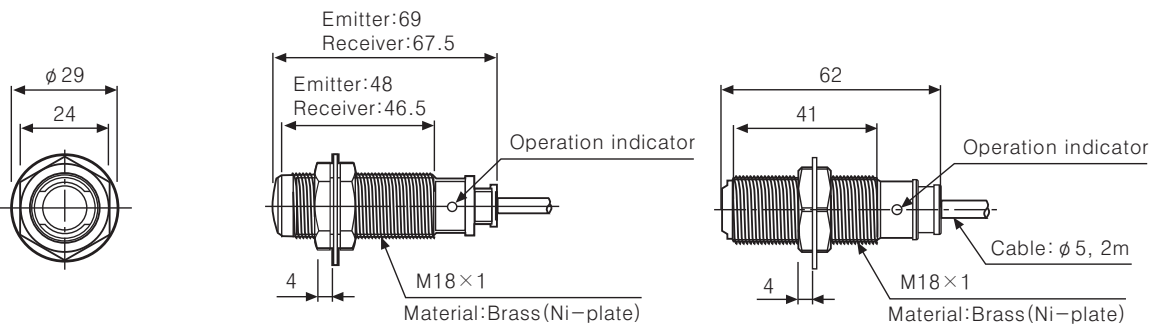
- BR100-DDT / BR100-DDT-P ●BR200-DDTN / BR200-DDTN-P
- BR400-DDT / BR400-DDT-P ●BR3M-MDT / BR3M-MDT-P (\*)



- BRP100-DDT / BRP100-DDT-P ●BRP200-DDTN / BRP200-DDTN-P
- BRP400-DDT / BRP400-DDT-P ●BRP3M-MDT / BRP3M-MDT-P (\*)



- BR4M-TDTD / BR4M-TDTD-P / BR4M-TDTL / BR4M-TDTL-P
- BR20M-TDTD / BR20M-TDTD-P / BR20M-TDTL / BR20M-TDTL-P



< BR4M Series >

< BR20M Series >

(Unit:mm)

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/Socket

(H) Temp. controller

(I) SSR/Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/Speed/Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/Logic panel

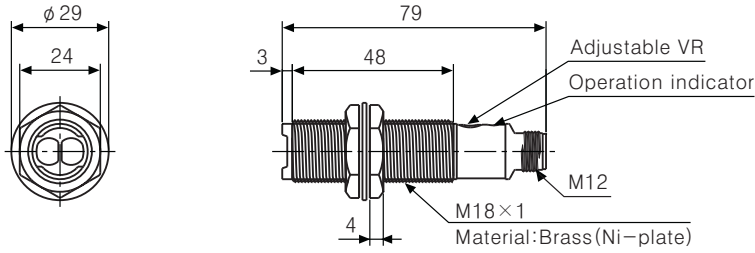
(S) Field network device

(T) Production stoppage models & replacement

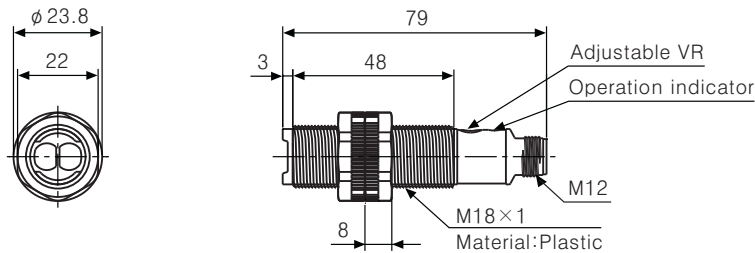
# BR Series

## ■ Dimensions

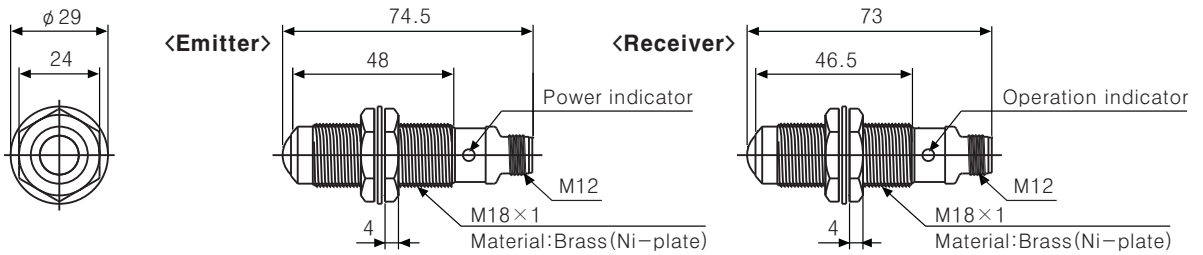
### ● BR100/200/400/3M-DDT(N)-C(-P)



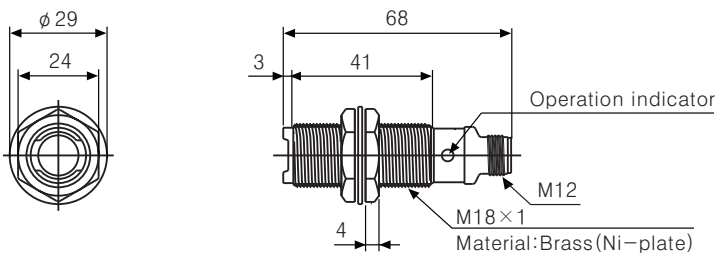
### ● BRP100/200/400/3M-DDT(N)-C(-P)



### ● BR4M-TDTD(L)-C(-P)



### ● BR20M-TDTD(L)-C(-P)



(Unit:mm)

## ■ Operation mode

Light ON mode	Receiver	[ ON OFF ]		Dark ON mode	Receiver	[ ON OFF ]	
	Operation indicator (LED)	[ ON OFF ]			Operation indicator (LED)	[ ON OFF ]	
	TR output	[ ON OFF ]			TR output	[ ON OFF ]	

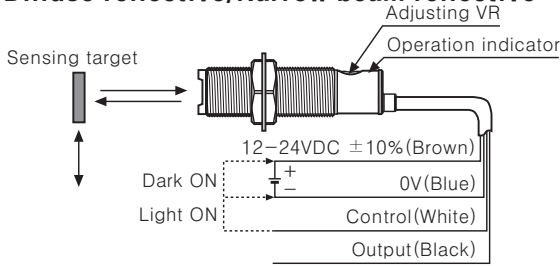
※ The control TR output will be held OFF for 0.5 sec. after supplied power in order to prevent malfunction of this photoelectric sensor (Diffuse reflective, retroreflective).

※ If the control output terminal is short-circuited or flow beyond rated current, the control signal will not be output normally due to protection circuit.

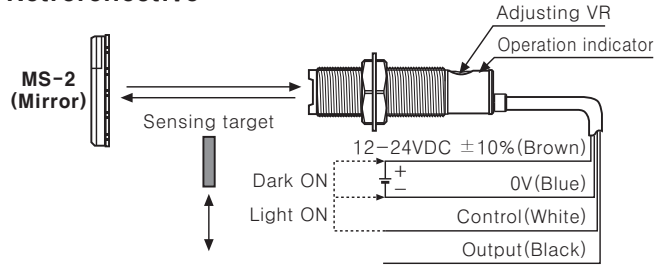
# DC Cylindrical Housing Type

## Connections

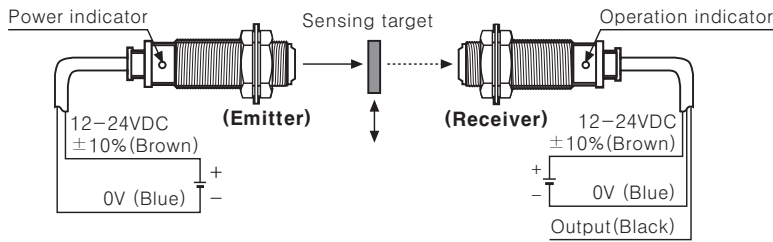
### Diffuse reflective/Narrow beam reflective



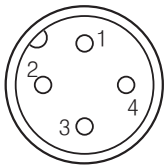
### Retroreflective



### Through-beam



## Connections



M12 Connector pin

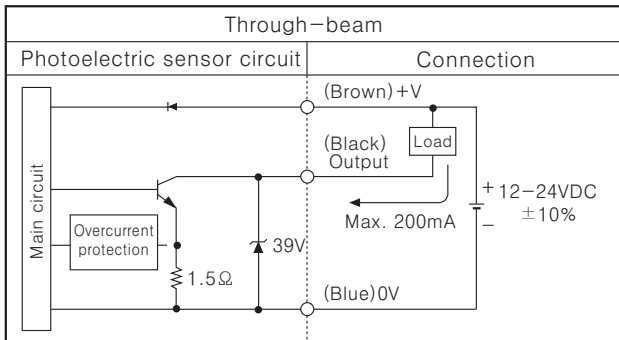
Connector pin No.	Cable colors	Application		
		Diffuse/Narrow beam reflective	Retroreflective	Through-beam
1	Brown	24VDC	24VDC	24VDC
2	White	CONTROL	N.C	GND
3	Blue	GND	GND	GND
4	Black	OUTPUT	N.C	OUTPUT

● Connector cable (Sold separately)

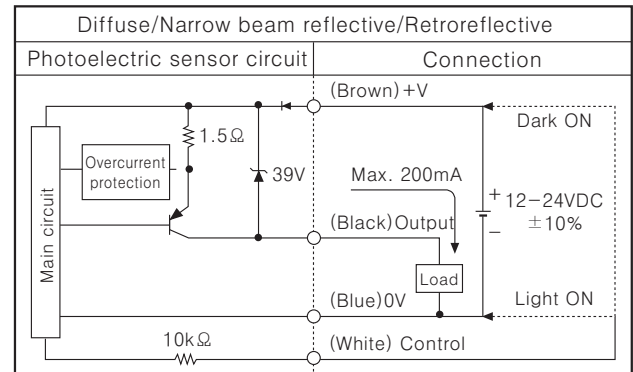
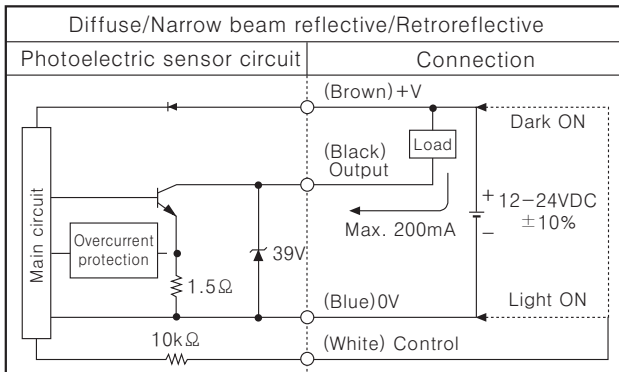
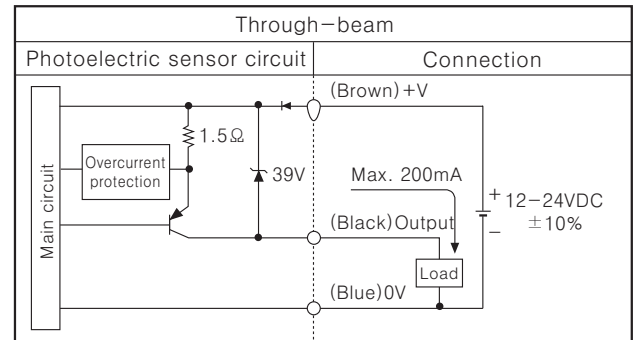
※ Please refer to G-5 for connector cable.

## Control output diagram

### NPN open collector output



### PNP open collector output



(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

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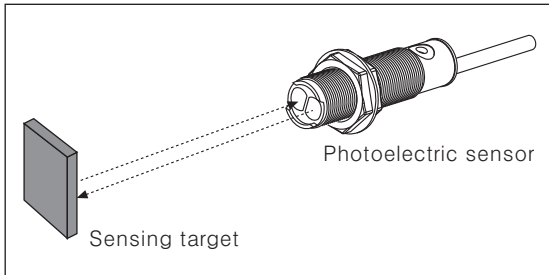
(T) Production stoppage models & replacement

## ■ Mounting and sensitivity adjustment

Please supply the power to the sensor after mount the emitter and the receiver facing each other, and then adjust an optical axis and the sensitivity as follow;

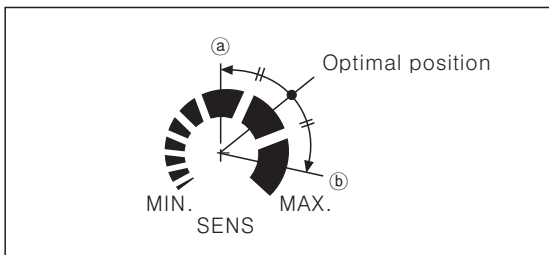
### ◎ Diffuse reflective/Narrow beam reflective type

1. The sensitivity should be adjusted depending on a sensing target or mounting place.



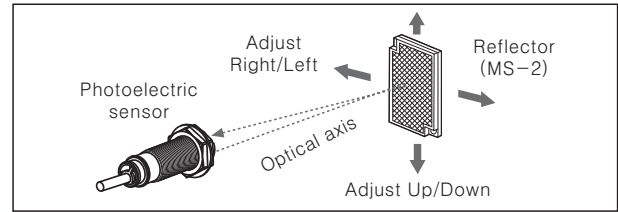
2. Set the target at a position to be detected by the beam, then turn the adjuster until position ① in the middle of the operation range of indicator from Min. position of the adjuster.
3. Take the target out of the sensing area, then turn the adjuster until position ② in the middle of the operation range of indicator. If the indicator does not turn on, max. position is position ②.
4. Set the adjuster in the middle of two switching position ①, ②.

※ The sensing distance indicated in the specification chart is that of non-glossy white paper in the target size 100×100mm or 50×50mm. Be sure that it can be different by size, surface and gloss of target.



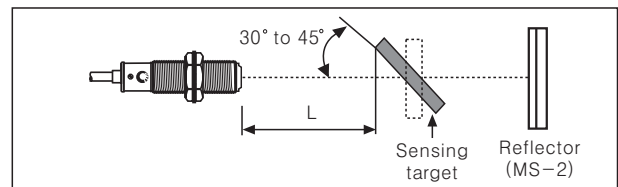
### ◎ Retroreflective type

1. Supply the power to the photoelectric sensor, after set the photoelectric sensor and the reflector (MS-2) facing each other.
  2. Set the photoelectric sensor in the middle of the operation range of indicator adjusting the reflector or the sensor right and left, up and down.
  3. Adjust up and down direction as the same.
  4. After adjustment, check the stability of operation putting the object at the optical axis.
- ※ If use more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.

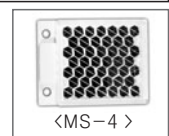


- ※ If use more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.
- ※ If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photo sensor. Therefore put enough space between the target and photoelectric sensor or the surface of target should be installed at an angle of 30° to 45° against optical axis. (When detecting target with high reflectance near by, photoelectric sensor with the polarizing filter should be used.)

※ Sensitivity adjustment : Please refer to the diffuse reflective type.



- ※ If the mounting place is too small, please use MS-4 instead of MS-2 for same sensing distance.



### ◎ Through-beam type

1. Supply the power to the photoelectric sensor, after mount the emitter and the receiver facing each other.
2. Set the receiver in center of position in the middle of the operation range of indicator adjusting the receiver and the emitter right and left, up and down.
3. Fix both units tightly after checking that the unit detect the target.

