

# E60H Series

## Diameter $\phi$ 60mm Hollow shaft type Incremental Rotary encoder

Line-up

### Features

- Diameter  $\phi$  60mm, Inner diameter of shaft  $\phi$  20mm
- Easy installation at narrow space
- Suitable for measuring angle, position, revolution, speed, acceleration and distance
- Power supply : 5VDC, 12–24VDC  $\pm$ 5%
- Various output types



**⚠ Please read "Caution for your safety" in operation manual before using.**

### Ordering information

<b>E60H</b>	<b>20</b>	<b>8192</b>	<b>3</b>	<b>N</b>	<b>24</b>	
Series	Shaft diameter	Pulse/1Revolution	Output phase	Output	Power supply	Cable
Diameter $\phi$ 60mm, hollow shaft type	$\phi$ 20mm	100, 1024, 5000, 8192	3 : A, B, Z 6 : A, $\bar{A}$ , B, $\bar{B}$ , Z, $\bar{Z}$	T : Totem pole output N : NPN open collector output V : Voltage output L : Line driver output(*)	5 : 5VDC $\pm$ 5% 24 : 12–24VDC $\pm$ 5%	Blank: Normal type (*) C: Cable outgoing connector type

\*Standard : E60H20-[PULSE]-3-N-24

\*The power of Line driver is only for 5VDC

\*Cable length : 250mm

### Specifications

Item		Diameter $\phi$ 60mm hollow shaft type of incremental rotary encoder		
Resolution(P/R)		<b>(Note1)</b>	100, 1024, 5000, 8192	
Electrical specification	Output phase	A, B, Z phase (Line driver output A, $\bar{A}$ , B, $\bar{B}$ , Z, $\bar{Z}$ phase)		
	Phase difference of output	Phase difference between A and B : $\frac{T}{4} \pm \frac{T}{8}$ (T=1cycle of A phase)		
	Control output	Totem pole output	<ul style="list-style-type: none"> <li>• Low <math>\Rightarrow</math> Load current:Max. 30mA, Residual voltage : Max. 0.4VDC</li> <li>• High <math>\Rightarrow</math> Load current:Max. 10mA, Output voltage(Power supply 5VDC):Min. (Power supply-2.0)VDC, Output voltage(Power supply 12–24VDC):Min. (Power supply-3.0)VDC</li> </ul>	
		NPN open collector output	Load current : Max. 30mA, Residual voltage : Max. 0.4VDC	
		Voltage output	Load current : Max. 10mA, Residual voltage : Max. 0.4VDC	
		Line driver output	<ul style="list-style-type: none"> <li>• Low <math>\Rightarrow</math> Load current : Max. 30mA, Residual voltage : Max. 0.4VDC</li> <li>• High <math>\Rightarrow</math> Load current : Max. 10mA, Output voltage(Power supply 5VDC) : Min. (Power voltage-2.0)VDC, Output voltage(Power voltage 12–24VDC) : Min. (Power voltage-3.0)VDC</li> </ul>	
	Response time (Rise/Fall)	Totem pole output	Max. 1 $\mu$ s	<ul style="list-style-type: none"> <li>• Measuring condition <math>\Rightarrow</math> Cable length : 2m, I sink = Max. 20mA</li> </ul>
		NPN open collector output	Max. 1 $\mu$ s	
		Voltage output	Max. 1 $\mu$ s	
		Line driver output	Max. 0.5 $\mu$ s	
	Max. Response frequency		300kHz	
	Power supply		<ul style="list-style-type: none"> <li>• 5VDC <math>\pm</math>5%(Ripple P-P:Max. 5%)</li> <li>• 12–24VDC <math>\pm</math>5%(Ripple P-P:Max. 5%)</li> </ul>	
	Current consumption		Max. 80mA(disconnection of the load), Line driver output : Max. 50mA(disconnection of the load)	
	Insulation resistance		Min. 100M $\Omega$ (at 500VDC megger between all terminals and case)	
Dielectric strength		750VAC 50/60Hz for 1 minute (Between all terminals and case)		
Connection		Cable outgoing type, 250mm cable outgoing connector type		
Mechanical specification	Starting torque	Max. 150gf · cm (0.015N · m)		
	Moment of inertia	Max. 110g · cm <sup>2</sup> (11 $\times$ 10 <sup>-5</sup> kg · m <sup>2</sup> )		
	Shaft loading	Radial : 5kgf, Thrust : 2.5kgf		
	Max. allowable revolution	<b>(Note2)</b>	6000rpm	
Vibration		1.5mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hours		
Shock		Max. 100G		
Ambient temperature		-10 to 70 $^{\circ}$ C (at non-freezing status), Storage : -25 to 85 $^{\circ}$ C		
Ambient humidity		35 to 85%RH, Storage : 35 to 90%RH		
Protection		IP50(IEC standard)		
Cable		$\phi$ 5mm, 5P, Length : 2m, Shield cable (Line driver output : $\phi$ 5mm, 8P)		
Accessory		Bracket		
Unit weight		Approx. 300g		

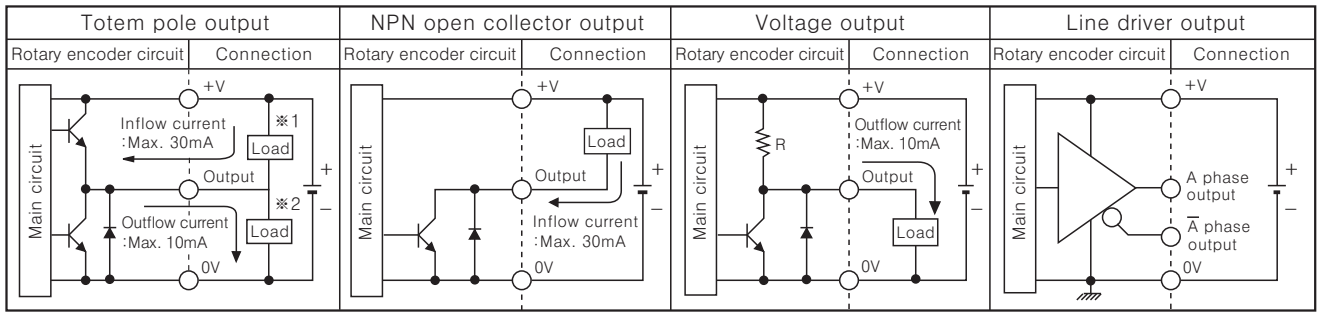
\* **(Note1)** Not indicated type is customizable.

\* **(Note2)** Max. allowable revolution  $\geq$  Max. response revolution **[Max. response revolution (rpm) =  $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec.}$ ]**

Make sure that max. response revolution should be lower than max. allowable revolution when selecting the resolution.

# Incremental $\phi$ 60mm Hollow Shaft Type

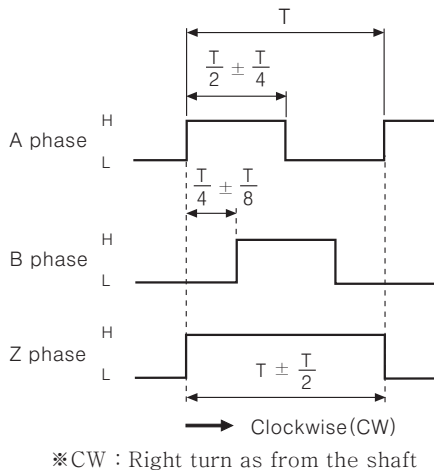
## Control output diagram



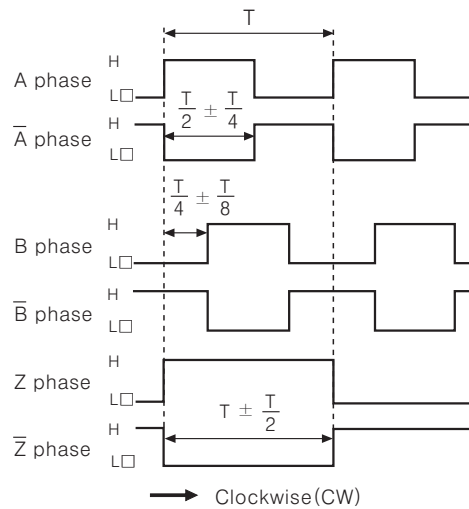
- Totem pole output type can be used for NPN open collector output type(\*1) or Voltage output type(\*2).
- All output circuits of A, B, Z phase are the same. (Line driver output is A,  $\bar{A}$ , B,  $\bar{B}$ , Z,  $\bar{Z}$ )

## Output waveform

- Totem pole output / NPN open collector output / Voltage output



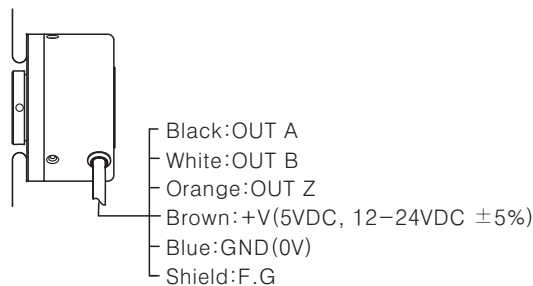
- Line driver output



## Connections

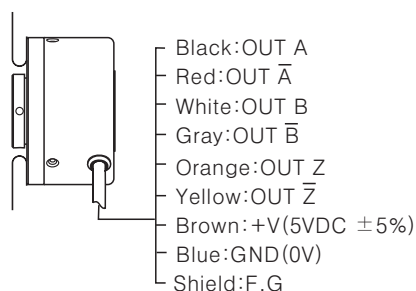
### Normal type

- Totem pole output / NPN open collector output / Voltage output



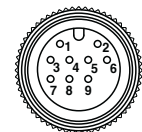
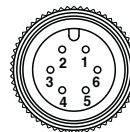
- \*Unused wires must be insulated.
- \*The metal case and shield cable of encoder should be grounded(F.G).

- Line driver output



### Cable outgoing connector type

- Totem pole output
- NPN open collector output
- Voltage output
- Line driver output



Totem pole output NPN open collector output Voltage output			Line driver output		
Pin No	Function	Cable color	Pin No	Function	Cable color
①	OUT A	Black	①	OUT A	Black
②	OUT B	White	②	OUT $\bar{A}$	Red
③	OUT Z	Orange	③	+V	Brown
④	+V	Brown	④	GND	Blue
⑤	GND	Blue	⑤	OUT B	White
⑥	F.G	Shield	⑥	OUT $\bar{B}$	Gray
			⑦	OUT Z	Orange
			⑧	OUT $\bar{Z}$	Yellow
			⑨	F.G	Shield

\*F.G(Field Ground) : It should be grounded separately.

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/Socket

(H) Temp. controller

(I) SSR/Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/Speed/Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/Logic panel

(S) Field network device

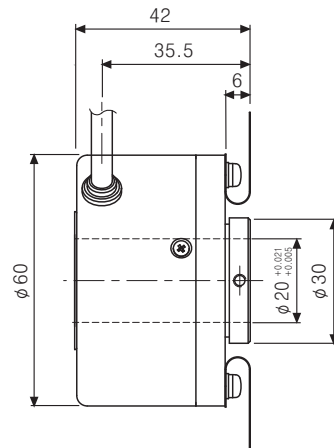
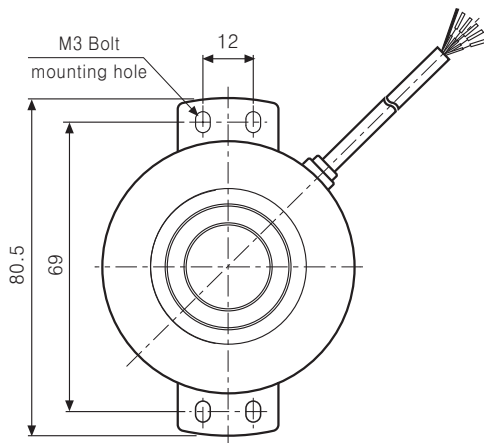
(T) Production stoppage models & replacement

# E60H Series

## Dimension

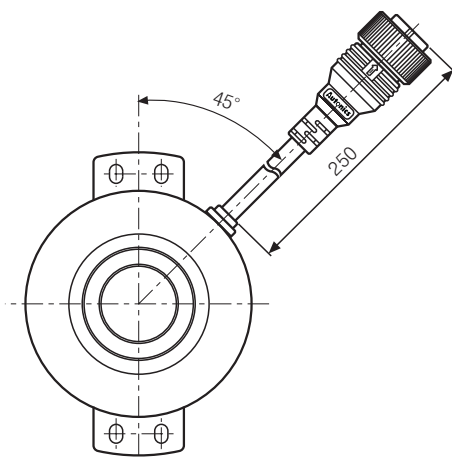
(Unit:mm)

### Normal type

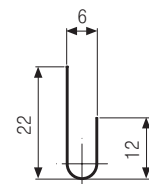
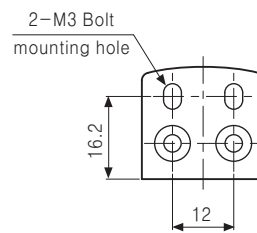


Cable for normal type $\phi$ 5mm, 5P(Line driver output:8P), Length:2000m, Shield cable
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### Cable outgoing connector type



### Bracket



\*Connector cable is customizable and see G-6 for specifications.